#### "APPROXIMATION ALGORITHMS"FOR SCHEDULING A SINGLE MACHINE TO MINIMIZE TOTAL LATE WORK"

by

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# APPROXIMATION ALGORITHMS FOR SCHEDULING A SINGLE MACHINE TO MINIMIZE TOTAL LATE WORK

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In the problem of scheduling a single machine to minimize total late work, there are n jobs to be processed, each of which has an integer processing time and an integer due date. The objective is to find a sequence of jobs which minimizes the total late work, where the late work for a job is the amount of processing of this job that is performed after its due date. Three families of approximation algorithms  $\{E_k\}, \{A_\epsilon\}$  and  $\{B_\epsilon\}$  are presented. Contained in the first family is a (1 + 1/k)approximation algorithm  $E_k$ , for any positive integer  $k \leq n$ , which uses truncated enumeration;  $E_k$  requires  $O(n^{k+1})$  time and O(n) space. The two other families  $\{A_\epsilon\}$  and  $\{B_\epsilon\}$  are fully polynomial approximation schemes which are based on the rounding of state variables in dynamic programming formulations. In the superior scheme, for  $0 < \epsilon < 1$ ,  $B_\epsilon$  is a  $(1 + \epsilon)$ -approximation algorithm which has a time requirement of  $O(n^2/\epsilon)$  and a space requirement of  $O(n/\epsilon)$ .

## 1. Introduction

The non-preemptive single machine total late work problem may be stated as follows. Each of n jobs (numbered  $1, \ldots, n$ ) is to be processed without interruption on a single machine which can handle only one job at a time. Job i  $(i = 1, \ldots, n)$ becomes available for processing at time zero, requires an integer processing time  $p_i$ and has an integer due date  $d_i$ . We assume that jobs are numbered in non-decreasing order of their due dates (EDD order) so that  $d_1 \leq \ldots \leq d_n$ . In any schedule, the late work  $V_i$  for job i is the amount of processing performed on i after its due date  $d_i$ . Thus, if job i is completed at time  $C_i$ , then  $V_i = 0$  if job i is early, i.e., if  $C_i \leq d_i$ ;  $V_i = C_i - d_i$  if job i is partially early, i.e., if  $d_i < C_i < d_i + p_i$ ; and  $V_i = p_i$  if job i is late, i.e., if  $C_i \geq d_i + p_i$ . Expressed differently, if  $T_i = \max\{C_i - d_i, 0\}$  is the tardiness of job i, then  $V_i = \min\{T_i, p_i\}$ . The objective is to find a processing order of jobs which minimizes the total late work  $\sum_{i=1}^n V_i$ .

This type of model is first studied by Blazewicz [1] who points out its relevance in the field of information processing. In a recent paper, Potts and Van Wassenhove [5] derive an algorithm for the preemptive version of this problem in which the processing of a job may be interrupted and resumed at a later time. This algorithm requires  $O(n \log n)$  time and generates at most one preemption. They also show that the non-preemptive problem is (binary) NP-hard. A key result is that an optimal non-preemptive schedule may be obtained by specifying a set of early and partially early jobs; these are sequenced first in EDD order followed by the remaining late jobs in an arbitrary order. This result is used in a pseudopolynomial dynamic programming algorithm which requires O(nUB) time, where UB is any upper bound on the minimum total late work. Computational results indicate that this algorithm can solve problems with up to 3000 jobs if processing times are small  $(p_i \leq 100 \text{ for } i = 1, ..., n).$ 

In this paper, we study approximation algorithms for the non-preemptive single machine total late work problem. When processing times are large, these algorithms are especially useful since the dynamic programming algorithm of Potts and Van Wassenhove may require excessive core storage. Let  $V^*$  denote the minimum value of the total late work and let  $V^A$  be the total late work when jobs are scheduled using a certain approximation algorithm A. We describe A as a  $\rho$ -approximation algorithm if  $V^A \leq \rho V^*$  for all problem instances.

In Section 2, we describe (1 + 1/k)-approximation algorithms  $E_k$ , for k = 1, ..., n, which are based on truncated enumeration. Algorithm  $E_k$  requires  $O(n^{k+1})$ time and O(n) space. Section 3 presents  $(1 + \epsilon)$ -approximation algorithms  $A_{\epsilon}$  and  $B_{\epsilon}$  for any  $\epsilon > 0$ , which are based on the rounding of state variables in dynamic programming formulations. For  $0 < \epsilon < 1$ , Algorithm  $A_{\epsilon}$  requires  $O(n^3/\epsilon)$  time and  $O(n^2/\epsilon)$  space, whereas  $B_{\epsilon}$  requires  $O(n^2/\epsilon)$  time and  $O(n/\epsilon)$  space. Since time requirements are polynomial in n and  $1/\epsilon$ , the families  $\{A_{\epsilon}\}$  and  $\{B_{\epsilon}\}$  are fully polynomial approximation schemes.

## 2. Truncated enumeration

#### 2.1. A lower bounding scheme

Our truncated enumeration algorithms have at their core a branch and bound algorithm. Lower bounds are obtained from the solution to the problem in which jobs of a set E are constrained so that they cannot be preempted and they cannot be late, whereas other jobs can be preempted. An algorithm to solve this problem in O(n) time (once an EDD sequence of jobs is known) is described below.

It is assumed that jobs are renumbered so that  $E = \{1, \ldots, e\}$ , where  $d_1 \leq \ldots \leq d_e$ . Firstly, suppose that  $\sum_{i=1}^{a} p_i \leq d_e$  for  $a = 1, \ldots, e$ . Thus, it is possible to construct a schedule in which all jobs of E are early. A lower bound is obtained by applying the following variant of a preemptive algorithm for the total late work problem [5]. Firstly, the maximum tardiness  $T_{\max}$  for an EDD sequence is computed. If  $T_{\max} = 0$ , then the EDD sequence is optimal with total late work equal to zero. Alternatively, if  $T_{\max} > 0$ , then a preemptive schedule is constructed from the EDD sequence by selecting  $T_{\max}$  units of processing to be repositioned as late work at the end of the schedule. The  $T_{\max}$  units of processing are chosen as close to the start of the EDD schedule as possible, although processing corresponding to jobs of E is not eligible for repositioning. It is easily verified that this procedure generates an optimal preemptive schedule with total late work equal to  $T_{\max}$ . Furthermore, at most one job is preempted. Once an EDD sequence of jobs is known, this variant of the preemptive scheduling algorithm requires O(n) time.

The alternative case that  $\sum_{i=1}^{a} p_i > d_a$  for some  $a \in E$ , where a is chosen as large as possible, remains to be discussed. We claim that there exists an optimal solution of our constrained problem in which jobs  $1, \ldots, a$  are sequenced first. To justify this, we observe that any processing on job j, where  $j \notin E$ , which is executed before job a, can be removed as late work to produce a corresponding decrease in the late work for job a. After computing their contribution to the total late work, jobs  $1, \ldots, a$  are removed from the problem by subtracting  $\sum_{i=1}^{a} p_i$  from the due dates of other jobs. Jobs are also removed as late work if their due dates become negative. For the remaining jobs, the procedure described above is applied to generate a lower bound.

#### 2.2. Description of the algorithms

We now present details of our family of truncated enumeration algorithms. Consider the following branch and bound algorithm. Lower bounds are computed by allowing preemption. If no job is preempted in the solution of the preemptive problem, then an optimal solution of the non-preemptive problem is obtained. Otherwise, a single job i is preempted. A binary branching rule fixes job i either to be late or non-late. In the former case, job j is discarded from the problem by including it in a set L of late jobs. In the latter case, job j is included in a set E of non-late jobs. As pointed out in Section 2.1, it is straightforward to allow for the jobs of E in the computation of lower bounds through preemptive scheduling. For each lower bound that is computed, a corresponding upper bound, obtained by setting any preempted job to be late, is evaluated. A node is fathomed if its lower bound is at least as large as the smallest upper bound that is currently available or if the EDD sequence of the jobs of E yields a late job, i.e., if the set E is infeasible. This algorithm delivers an optimal solution after a maximum of  $2^{n+1} - 1$  search tree nodes are generated.

Our truncated enumeration algorithms  $E_k$ , for k = 1, ..., n, artificially fathom nodes to reduce computational requirements. More precisely, a node of the search tree is discarded if exactly k jobs are constrained to be late, i.e., if |L| = k. In algorithm  $E_n$ , no nodes are artificially fathomed, so it reduces to the branch and bound algorithm which generates an optimal solution. More generally, algorithms  $E_k$  only deliver approximate solutions because, on full exploration of the search tree, each optimal solution is found at a successor of an artificially fathomed node.

#### 2.3. Analysis of the algorithms

Our main result of this section shows that  $E_k$  is a (1 + 1/k)-approximation algorithm.

**Theorem 1.** For k = 1, ..., n,  $E_k$  is a (1 + 1/k)-approximation algorithm with time and space requirements of  $O(n^{k+1})$  and O(n) respectively.

**Proof.** Unless all optimal schedules correspond to the decisions taken at artificially fathomed nodes, algorithm  $E_k$  generates an optimal solution. Thus, we consider the case that an optimal solution is consistent with an artificially fathomed node in which the jobs of  $L = \{j_1, \ldots, j_k\}$  are constrained to be late. Let  $j \in L$  be chosen such that  $p_j = \min\{p_{j_1}, \ldots, p_{j_k}\}$ . Since jobs  $j_1, \ldots, j_k$  are late in an optimal schedule, we have

$$V^* \ge \sum_{i=1}^k p_{j_i} \ge k p_j. \tag{1}$$

At some predecessor node in the search tree, job j is the preempted job in the lower bounding computation. Since this is a predecessor node, an optimal schedule is consistent with the sets of jobs constrained to be late and non-late. Let v be the lower bound at this node. Setting job j to be late gives an upper bound which algorithm  $E_k$  may select. Thus,

$$V^{E_k} < v + p_j.$$

Using the information that v is a lower bound on the value  $V^*$  of an optimal schedule

and applying (1) yields

$$V^{E_k} < (1+1/k)V^*,$$

which is the required inequality.

The time and space bounds are now established. Since at each node of the search tree for algorithm  $E_k$  we have  $|L| \leq k$ , the tree contains a maximum of  $O(n^k)$  nodes, each of which requires O(n) time for the computation of a lower bound. Thus, the time complexity of  $E_k$  is  $O(n^{k+1})$ . Clearly, it requires O(n) space if a newest active node search strategy is employed.  $\Box$ 

Algorithm  $E_k$  appears to be mainly of theoretical interest unless k is small. However,  $E_1$  is of special interest. A simplified statement of algorithm  $E_1$  is as follows. First solve the preemptive problem to find any preempted job j; if there is no preempted job, then an optimal solution is obtained. Setting job j to be late gives one non-preemptive schedule which is evaluated. Job j is included in a set Eof jobs which are constrained to be non-late in all subsequent computations. The procedure continues until either E becomes infeasible or until there is no preempted job in the solution of the preemptive problem. Algorithm  $E_1$  selects the best of the non-preemptive schedules generated.

Theorem 1 shows that  $E_1$  is a 2-approximation algorithm. The following instance shows that no stronger bound on the performance of  $E_1$  can be derived. There are n jobs, where  $n \ge 3$ , with processing times and due dates defined by  $p_1 = n - 2$ ,  $d_1 = n - 2$ , and  $p_i = n - 1$  and  $d_i = (i - 1)n - i$  for i = 2, ..., n. In a solution of the preemptive scheduling problem, job 1 is late and job 2 is preempted with one unit of its processing scheduled after its due date. By setting job 2 to be late, the total late work is 2n - 3. When job 2 is constrained to be non-late, it is removed from the problem by setting  $d_i = (i-2)n - i + 1$  for i = 3, ..., n. In subsequent iterations where  $E = \{2, ..., i-1\}$ , sequences (2, ..., i-1, i+1, ..., n, 1, i)with job 1 and job *i* late are generated for i = 3, ..., n, which have total late work equal to 2n + i - 5. Finally, when  $E = \{2, ..., n\}$ , the sequence (2, ..., n, 1) is generated, for which the total late work is again equal to 2n - 3. An optimal sequence is (1, 3, ..., n, 2) in which job 2 is late and all other jobs are early. Thus, we have  $V^{E_1} = 2n - 3$  and  $V^* = n - 1$ , giving  $V^{E_1}/V^* = 2 - 1/(n-1)$ . Therefore, the ratio  $V^{E_1}/V^*$  can be arbitrarily close to 2, which demonstrates that  $E_1$  is no better than a 2-approximation algorithm.

## 3. Dynamic programming and rounding

The families of approximation algorithms  $\{A_{\epsilon}\}$  and  $\{B_{\epsilon}\}$ , which we describe and analyze in this section, are based on the rounding of state variables in dynamic programming formulations. This methodology is proposed by Sahni [6] for various single and parallel machine scheduling problems and has subsequently been used for a variety of scheduling problems by Gens and Levner [2], Hall and Shmoys [3] and Lawler [4].

The  $(1+\epsilon)$ -algorithms  $A_{\epsilon}$  and  $B_{\epsilon}$  each have two phases. In both algorithms, the first phase applies algorithm  $E_1$  to generate an upper bound in  $O(n^2)$  time and O(n)space. If  $V^{E_1} = 0$  or  $\epsilon \ge 1$ , the second phase is not executed since  $V^{E_1} \le (1+\epsilon)V^*$ : this inequality is apparent when  $V^{E_1} = 0$  and is deduced from Theorem 1 when  $\epsilon \ge 1$ . However, if  $V^{E_1} > 0$  and  $\epsilon < 1$ , the second phase uses dynamic programming with rounded state variables to generate an approximate solution. The subsequent analysis concentrates only on those cases in which the second phase is required.

Our first approximation scheme  $\{A_{i}\}$  has at its core the dynamic programming algorithm  $DP_t$  of Potts and Van Wassenhove. The subscript t in  $DP_t$  is used to denote that time is a state variable: later we use a dynamic programming algorithm having a different state variable. The algorithm uses a recursion defined on values  $f_j(t)$  for j = 1, ..., n; at most UB + 1 values of t are considered, where UB =  $V^{E_1}$ is the upper bound found in the first phase of  $A_{\epsilon}$ . The function  $f_j(t)$  represents the total late work on jobs  $1, \ldots, j$  when all early and partially early jobs are completed at time t. The time complexity of this algorithm is  $O(nV^{E_1})$  and its space requirement is  $O(V^{E_1})$ . In the second phase of  $A_{\epsilon}$ , a rounded problem  $\tilde{P}$  is created by, if necessary, rounding down each processing time to the nearest integer multiple of K, where  $K = \epsilon V^{E_1} / (n(n+1))$ . Thus, job i (i = 1, ..., n) has processing time  $\tilde{p}_i = K\lfloor p_i/K \rfloor$  and due date  $\tilde{d}_i = d_i$  in  $\tilde{P}$ . Algorithm  $A_\epsilon$  takes as its schedule an optimal sequence  $\sigma_t$  for  $\tilde{P}$ , which is obtained by applying DP<sub>t</sub>. In this application of  $DP_t$ , only state variables t which are integer multiples of K are considered. Thus, when K > 1, the number of recursion equations to be solved reduces from  $O(nV^{E_1})$ in the original problem P to  $O(nV^{E_1}/K)$  in problem  $\tilde{P}$ . Clearly, if  $K \leq 1$ , there is no advantage in considering problem  $\tilde{P}$ .

The following result establishes bounds on the performance of the family  $\{A_{\epsilon}\}$ .

**Theorem 2.** For any  $\epsilon$  such that  $0 < \epsilon < 1$ ,  $A_{\epsilon}$  is a  $(1+\epsilon)$ -approximation algorithm with time and space requirements of  $O(n^3/\epsilon)$  and  $O(n^2/\epsilon)$  respectively.

**Proof.** Let  $\tilde{V}^*$  denote the minimum value of the total late work for problem  $\tilde{P}$ . Since  $\tilde{P}$  is obtained from the original problem P by reducing processing times, its minimum total late work provides a lower bound on the total late work for problem P. Thus,

$$\tilde{V}^* \le V^*. \tag{2}$$

Consider now the increase in the total late work for the sequence  $\sigma_{\epsilon}$  that arises through increasing the processing time of job i (i = 1, ..., n) from its value  $K[p_i/K]$ in  $\tilde{P}$  to  $p_i$  in P. The maximum increase in any processing time is less than K. Thus the late work of the first job of  $\sigma_{\epsilon}$  increases by less than K, the late work of the second job of  $\sigma_{\epsilon}$  increases by less than 2K, etc., to give a total increase in late work of less than n(n + 1)K/2. Thus,

$$V^{A_{\epsilon}} < \tilde{V}^* + n(n+1)K/2.$$
(3)

Combining (2) and (3) and substituting for K, we obtain

$$V^{A_{\epsilon}} < V^* + \epsilon V^{E_1}/2. \tag{4}$$

Since  $E_1$  is a 2-approximation algorithm,  $V^{E_1} \leq 2V^*$ . Substituting this inequality into (4) shows that  $A_{\epsilon}$  is a  $(1 + \epsilon)$ -approximation algorithm.

We now establish the time and space bounds for the solution of problem  $\tilde{P}$  by algorithm DP<sub>t</sub>. The number of recursion equations which are solved is  $O(nV^{E_1}/K)$ . Substituting for K yields the time bound of  $O(n^3/\epsilon)$ . Similarly, the minimum storage required to solve the recursion equations is  $O(V^{E_1}/K)$ , which produces the space bound of  $O(n^2/\epsilon)$ .  $\Box$ 

The analysis in the proof of Theorem 2 shows that the conversion of an optimal solution of problem  $\tilde{P}$  into an approximate solution of problem P increases each

processing time by close to K in the worst case. This has a cumulative effect on completion times and, consequently, late work contributions are increased by up to  $K, 2K, \ldots, nK$ . Thus, the increase in total late work is  $O(n^2K)$  in the worst case. If this cumulative effect was not present, the value of K could be increased to  $O(\epsilon V^{E_1}/n)$ , thereby reducing the time and space complexity. We now describe an alternative approximation scheme which achieves this desired aim.

As observed previously, algorithm  $DP_t$  is based on the determination of values  $f_j(t)$ , representing the total late work for jobs  $1, \ldots, j$  when early and partially early jobs are completed at time t. We now propose an essentially equivalent dynamic programming algorithm  $DP_{\nu}$  in which the state variable t and the function definition are interchanged. More precisely, let  $g_i(v)$  denote the minimum completion time of early and partially early jobs when jobs  $1, \ldots, j$  are scheduled so that their total late work is v. For each job j, the values  $v = 0, \ldots, UB$  are considered, where we use the upper bound UB =  $V^{E_1}$ . Having determined  $g_{j-1}(0), \ldots, g_{j-1}(V^{E_1})$ , the values of  $g_j(v)$  are computed as follows. We start by setting values  $g_j(v) = g_{j-1}(v-p_j)$  for v = $p_j, \ldots, V^{E_1}$ , based on the assumption that job j is late. Under the assumption that job j is early or partially early, each entry  $g_{j-1}(v)$ , where  $g_{j-1}(v) < d_j$ , generates a schedule for jobs  $1, \ldots, j$  with a total late work of  $v' = v + \max\{g_{j-1}(v) + p_j - d_j, 0\}$ and a total processing time for early and partially early jobs of  $p' = g_{j-1}(v) + p_j$ . If  $p' < g_j(v')$ , then we reset  $g_j(v') = p'$ ; otherwise  $g_j(v')$  remains unchanged. Initialization sets  $g_0(0) = 0$  and  $g_j(v) = \infty$  for  $j \neq 0$  or  $v \neq 0$ . The minimum total late work is the smallest value of v for which  $g_n(v)$  is finite. As is the case for  $DP_t$ , algorithm  $DP_{v}$  requires  $O(nV^{E_1})$  time and  $O(V^{E_1})$  space.

We now give details of our second family of approximation algorithms  $\{B_{\epsilon}\}$ ,

which are based on algorithm  $DP_{v}$ . In the second phase of  $B_{\epsilon}$ , a rounded problem  $\bar{P}$  is created by, if necessary, rounding down the late work contribution for each each job to the nearest integer multiple of L, where  $L = \epsilon V^{E_1}/(2n)$ . Thus, the late work for job i (i = 1, ..., n) in  $\bar{P}$  when it is completed at time t is  $L\min\{\max\{\lfloor (t-d_i)/L \rfloor, 0\}, \lfloor p_i/L \rfloor\}$ . Algorithm  $B_{\epsilon}$  takes as its schedule an optimal sequence  $\pi_{\epsilon}$  for problem  $\bar{P}$ , which is obtained by applying  $DP_{v}$ . Since in this application of  $DP_{v}$  only state variables v which are integer multiples of L are considered, the number of recursion equations to be solved is  $O(nV^{E_1}/L)$ .

We proceed to establish bounds on the performance of the family  $\{B_{\epsilon}\}$ .

**Theorem 3.** For any  $\epsilon$  such that  $0 < \epsilon < 1$ ,  $B_{\epsilon}$  is a  $(1+\epsilon)$ -approximation algorithm with time and space requirements of  $O(n^2/\epsilon)$  and  $O(n/\epsilon)$  respectively.

**Proof.** Let  $\overline{V}^*$  denote the minimum value of the total late work for problem  $\overline{P}$ . Clearly,

$$\bar{V}^* \le V^* \tag{5}$$

since  $\bar{P}$  is obtained from the original problem P by reducing late work contributions. Consider now the increase in the total late work for the sequence  $\pi_{\epsilon}$  that is incurred when the late work of each job increases from its rounded to its true value. The late work of each job increases by less than L to give a total increase of less than nL. Therefore,

$$V^{B_*} < \bar{V}^* + nL. \tag{6}$$

Combining (5) and (6) and substituting for L yields

$$V^{B_{\epsilon}} < V^* + \epsilon V^{E_1}/2. \tag{7}$$

Substituting into (7) the inequality  $V^{E_1} \leq 2V^*$ , which is valid because  $E_1$  is a 2-approximation algorithm, shows that  $B_{\epsilon}$  is a  $(1 + \epsilon)$ -approximation algorithm.

We now establish the time and space bounds for the solution of problem  $\overline{P}$  by  $DP_{v}$ . Recalling that the number of recursion equations solved is  $O(nV^{E_{1}}/L)$ , we use  $L = \epsilon V^{E_{1}}/(2n)$  to obtain the time bound of  $O(n^{2}/\epsilon)$ . Similarly, the minimum storage of  $O(V^{E_{1}}/L)$  values yields a space bound of  $O(n/\epsilon)$ .  $\Box$ 

Theorems 2 and 3 show  $\{B_{\epsilon}\}$  to be a more efficient approximation scheme than  $\{A_{\epsilon}\}$ . However,  $\{A_{\epsilon}\}$  can be regarded as a more natural family, since  $A_{\epsilon}$  is derived from the easily implemented dynamic programming algorithm DP<sub>t</sub>.

Lastly, it is appropriate to comment on the relative merits of the algorithms of this section and algorithms  $E_k$ , for k = 1, ..., n, of Section 2. Suppose  $\epsilon = 1/k$ . Although  $A_{\epsilon}$  and  $B_{\epsilon}$  are clearly superior in terms of time requirements, algorithm  $E_k$  has much smaller space requirements. Thus, no definitive conclusion can be drawn as to whether the truncated enumeration algorithms or the schemes based on dynamic programming and rounding are preferred.

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		Mars 1988.	88/35	Mihkel M. TOMBAK	"A strategic analysis of investment in flexible manufacturing systems", July 1988.
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	and Merre HILLION	claims asset pricing models", October 1988.			asset structure of the firm", December 1988.
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	Reinhard ANGELMAR	effects of time, culture, and performance on			
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		organisation", January 1989.	89/18	Srinivasan BALAK- RISHNAN and	"Information asymmetry, market failure and joint-ventures: theory and evidence",
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	Helimut SCHÜTTE	and their effects on the production structure			
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	Bruno GERARD and Pierre HILLION	of the assets in place and the growth opportunities of the firm", December 1988.	89/21	Arnoud de MEYER and Kasra FERDOWS	"Influence of manufacturing improvement programmes on performance", April 1989.
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	Jean-Claude LARRECHE	and geographic coverage", May 1989.		Tawfik JELASSI	supported conflict resolution", July 1989.
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	Nittin NOHRIA	managing corporate-division relationships in			1989.
		the M-Form organisation", May 1989.			
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					exchange market", December 1989.
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	and Lydia PRICE	results", September 1989.			
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	Lars-Hendrik RÖLLER	multiproduct technologies", September 1989.	90/01	<b>B. SINCLAIR-DESGAGNÉ</b>	"Unavoidable Mechanisms", January 1990.
	and Mihkel TOMBAK		TM/EP/AC		
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(EP,TM)	and Mihkel TOMBAK	technologies", October 1989.	EP		Adjustment, and the Behaviour of European
(1.1.)					Manufacturing Employment", January 1990.
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(OB)	Daphna ZEVADI,	three-country comparative study", October	90/03	Arnoud DE MEYER	"Management of Communication in
	Alain NOEL and	1989.	ТM		International Research and Development",
	Mihkel TOMBAK				January 1990.
			00.00 Å	- · · · · · · · · · · · · · · · · · · ·	
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(TM)	Lee SCHRUBEN	discrete event simulation models", October	FIN/EP	Eric RAJENDRA	Financial Services Industry: From
		1989.			Fragmentation to Integration", January 1990.
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(All)	Arnoud DE MEYER	issues: The impact of national culture",	FIN/EP	Bertrand JACQUILLAT	and Beyond", January 1990.
		October 1989.			

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FIN/EP	Eric RAJENDRA	Implications of Structural Change for Key	90/17	Nathalie DIERKENS	"Information Asymmetry and Equity Issues",
		Market Participants to and Beyond 1992",	FIN		Revised January 1990.
		January 1990.			
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TM	Hans-Jakob LÜTHI	DSS: Putting Theory Into Practice", January	FIN/EP		January 1990.
		1990.			·
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		1990.	ТМ		Innovation", February 1990.

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90/30	Lars Tyge NIELSEN	"The Expected Utility of Portfolios of	FIN/EP	Itzhak SWARY and	<b>Announcement of Interstate Banking</b>
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MKT/EP	Roger BETANCOURT	February 1990.	MKT	Wilfried VANHONACKER	Marketing Research", (Revised April 1990).
90/32	Srinivasan BALAK-	"Information Asymmetry, Adverse Selection	90/43	Robert KORAJCZYK and	"Equity Risk Premia and the Pricing of
SM	<b>RISHNAN</b> and	and Joint-Ventures: Theory and Evidence",	FIN	Claude VIALLET	Foreign Exchange Risk", May 1990.
	Mitchell KOZA	Revised, January 1990.			
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	Christine PEARSON			André LAURENT	1990.
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90/34	Jean DERMINE	"The Gains from European Banking	ТМ	Piero BONISSONE	Reasoning: The Possibilistic Connection",
FIN/EP		Integration, a Call for a Pro-Active			May 1990.
		Competition Policy", April 1990.			
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EP		Varying Risk Premia in the Term Structure			Sample Forecasting Accuracy".
		of Nominal Interest Rates", December 1988,	00145		48
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90/36	Arnoud DE MEYER	"An Empirical Investigation of		WIINES VANHONACKER	Experiments: Limitations on the Use of Meta-Analysis Results in Bayesian
TM	AIRAG DE METER	Manufacturing Strategies in European			Updating", Revised May 1990.
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90/37	William CATS-BARIL	"Executive Information Systems: Developing	EP		Interest Rates: Out-of-Sample Forecasting
TM/OB/SM		an Approach to Open the Possibles", April			Performance", June 1990.
		1990.			
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90/38	Wilfried VANHONACKER	"Managerial Decision Behaviour and the	ТМ		Answer Nall Queries", June 1990.
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		Models", (Revised February 1990).	90/50	Daniel COHEN and	"Price and Trade Effects of Exchange Rates
<b>00</b> / <b>0</b> /			EP	Charles WYPLOSZ	Fluctuations and the Design of Policy
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EP		and Monetary Union", June 1990.	90/65 EP	Charles WYPLOSZ	"A Note on the Real Exchange Rate Effect of German Unification", August 1990
90/54	Damien NEVEN and	"European Financial Regulation: A			-
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EP	Stefan GERLACH	Balance", (Revised July 1990).	90/67 TM/SE/FIN	Soumitra DUTTA and Piero BONISSONE	"Integrating Prior Cases and Expert Knowledge In a Mergers and Acquisitions Reasoning System",
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		Manufacturing Sector*, July 1990	90/68 TM/SE	Soumitra DUTTA	"A Framework and Methodology for Enhancing the Business Impact of Artificial Intelligence
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		Industry", August 1990	MKT	Hubert GATIGNON	Empirical Analysis", September 1990
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EP	Menno VAN DUK	Netherlands", August 1990	SM	Nitin NOHRIA	Subsidiary Relations in MNCs", October 1990

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90/76	Wilfried VANHONACKER	*Managerial Decision Behaviour and the Estimation
MKT		of Dynamic Sales Response Models",
		Revised October 1990
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		Autocorrelation Test", October 1990
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EP	Siefan GERLACH	Unification: The Ostmark - DM Rate",
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TM		Bernoulli Process", October 1990
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